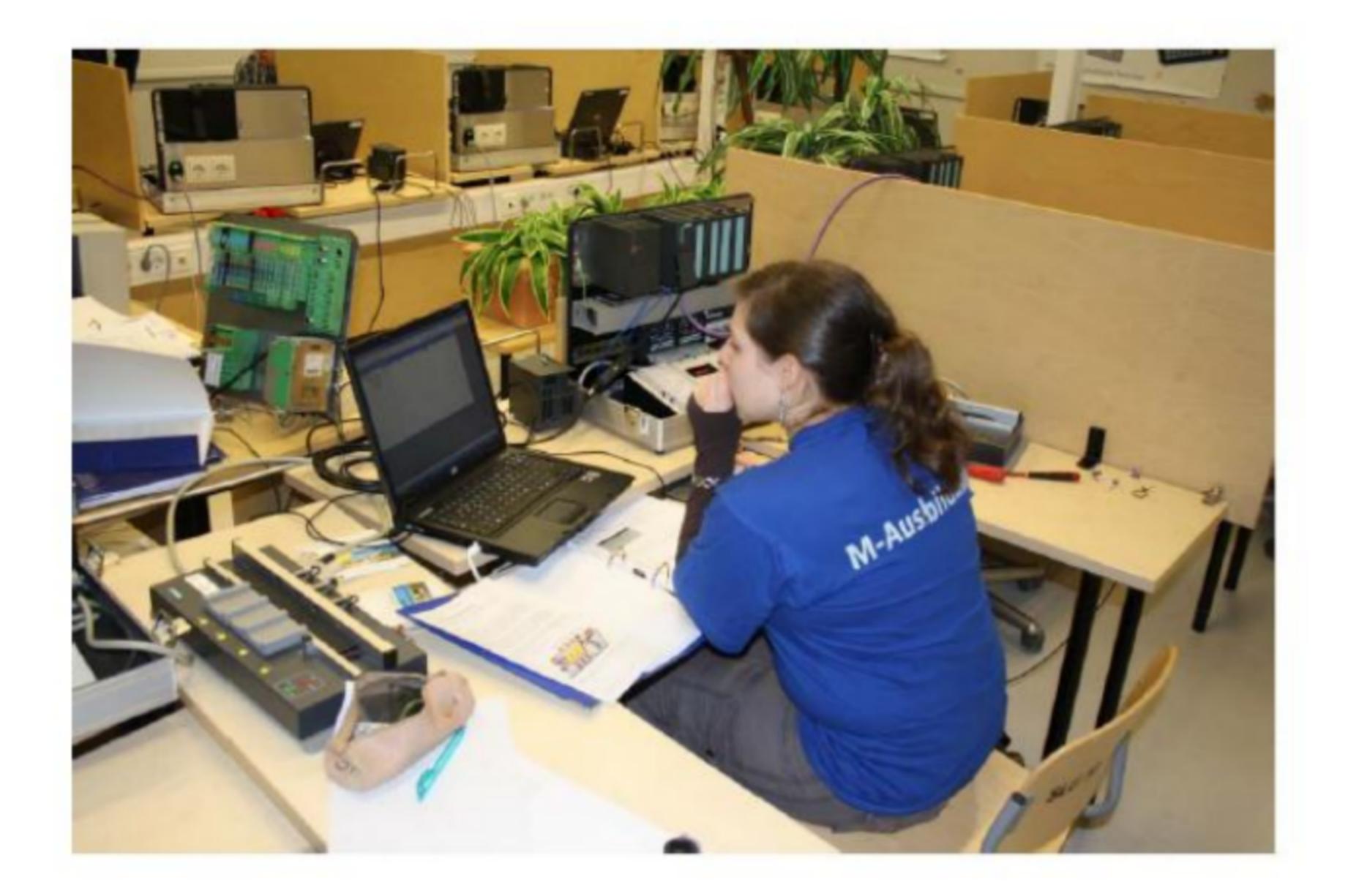




MODULE BUS SYSTEMS



The PLC-Module is designed for students which have automation technology as an essential part of their curriculum. Students that take part in the module should have basic knowledge of PLC-programming. In the module student must work mostly in pair's or groups, so good teamwork skills is needed. During the three week training the students will learn basic's of what is the main idea of industrial bus system's and how some of those are configured and build up. In the module there is also fault finding and diagnostic lessons. During the training the students can also see how industrial bus systems are used in local industrial companies and they also have some work to do there.

In the last week there is written test which student must past before he can take part of skills demonstration test.

Location in VQTS -matrix

He/She can use written maintenance on mechatronic systems of mechatronic systems and an equipment of mechatronic systems and an equipment of mechatronic systems and an equipment of mechatronic systems and facilities of mechatronic systems and production lines and production	Competence	Steps of competence de	velopment								
He/She can use written instructions to install and dismantling mechatronic systems and facilities of mechatronic systems. 3. Installing mechatronic components (e.g., sensors, actuators, drives, motors, transport systems, racks) that form a functional group of mechatronic systems. 4. He/She is able to install and adjusting mechatronic components (e.g., mechanics) in systems and production lines. 5. Installing mechatronic components (e.g., mechanics) in systems and production lines. 6. He/She is able to install and adjust the components (e.g., mechanics) in systems and production lines. 7. Installing mechatronic components (e.g., mechanics) in systems and production lines. 8. He/She can use machatronic components (e.g., mechanics) in systems and production lines. 8. He/She can use machatronic systems and facilities on the basis of client needs and site plans for mechatronic systems and facilities on the basis of client needs and site plans and can use basic CAD applications. 8. Personal production designs and customer requirements) the individual components of mechatronic systems and facilities on the basis of simple mechatronic systems and facilities on the basis of client needs and site plans and can use basic CAD applications. 8. Personal production designs and customer requirements) the individual components in site plans. 8. Personal production designs and customer requirements) the individual components in form of the care provide simple designs and customer requirements in the devices and site plans and can use basic CAD applications. 8. Personal production designs and customer to facilities on the basis of the devices and site plans and can use basic (CAD applications.) and is able to use CAD's more advanced functions, (e.g., mechanics), and the devices and t	1. Maintaining and assuring the reliability of mechatronic	the basic scheduled maintenance on mechatronic machines and systems and adhere to the equipment	the maintena procedures f mechatronic such as the service docu and mainten plans and, if with new cha can make the necessary		tenance troises for systems operance the use of documents intenance to intenance the the troises of troises of the troises of troises		maintenance to a troublefree operation of mech systems. In additional modify operational sequences to implement qual assurance		necessary procedures for remechatronic developments, and can schedule the man qualityassurance	r maintenance of levices and can maintenance and	
and adjusting mechatronic components (e.g., individual electropneumatic valves, sensor and actuator units). 4. Designing, adapting, adapting, and building mechatronic systems and folialities on the basis of client needs and site plans site plans 4. Designing, adapting, adapting, adapting, and building mechatronic systems and folialities on the basis of client needs and site plans 4. Designing, adapting, adapting, adapting, and building mechatronic systems and folialities on the basis of client needs and site plans 4. Designing, adapting, adapting, adapting, adapting, adapting, and building mechatronic systems on the basis of client needs and site plans 4. Designing, adapting, adapti	and dismantling mechatronic systems and facilities	instructions to install and dismantle individual com (e.g., sensors, actuators, drives, motors systems, racks) that form a functional gromechatronic systems.	ponents , transport oup of	He installation distributed in the control of the c	stallation a smantling of stems that see several to get a check the e coveral systems and check the e coveral systems.	nd of mechan echnolog nics, neumatic chanics, set up the chnology e effi cier ystem.	ies s, ncy of	mechatr the cons their ove ability to both exis	onic solutions for struction of production rall function, and, in ad sting difi ed standard com	on lines, assure dition, can use ponents.	
adapting, and building mechatronic systems and facilities on the basis of client needs and site plans are leading and build mechatronic systems and cartificate individual components for mechatronic systems. He/ she can provide designs and escriptions of mechatronic subsystems and can use basic CAD applications. CAD	and adjusting mechatronic components in systems and production	standardized mechatronic components individual electropneuma	s (e.g.,	m (e m	djust compo echatronic .g., linear o easuring s	onents of subsyste drives, ystems,		mechatr that incli- instrume control (associate test the assure t	onic facilities ude diverse technological entation and (&C) equipment, adjuded parameters, facilities overall function	ogies and just the	
	adapting, and building mechatronic systems and facilities on the basis of client needs and	machine tools controlled either manually or via computerprogram to fabricate (according to production designs and customer requirements) the individual components for mechatronic systems. He/ she can provide simple designs and descriptions of mechatronic subsystems and can use basic CAD	build simple mechatroni subsystems by using engineering drawing an can install the devices according to specifi conduction needs. He/ She can according extensive knowledge of standards and regulations (e.g., on surface treatments) and is able to use CAD's more advanced functions (e.g., interference	ic s d	build mechatro systems by using l original construct technique previously designed parts. He fully understar CAD functions can documen system developm (e.g., parts lists descriptio of functio operating	both ion es and y /She and t ents i, ens n,	design and bui autonor mechat subsyst and, wi suitable measur and testing facilities assess necess product accurac He/She docume the resi with qualityo	id nous ronic tems the ing s, can the ary ion y, can ent ults	He/She can make independent adaptations to the various devices (including selection of drives, sensors, PLC) and can use CNC programs for building the system. He/She can, through a digital mock up, assemble and simulate the functioning system and use computeraided computations (e.g., FEM). He/She can perform cost-benefit analyses (e.g., as a basis for deciding whether components should be bought or individually	independently develop complex mechatronic systems and can calculate the economic usefulness of the system. He/She can optimise CNC programs for the manufacturing of complex mechatronic devices and systems and monitor the automated quantity of an open loop control	





mechatronic systems into operation and providing clients with technical and economic support	according to specifications and blueprints, put mechatronic devices into operation and provide support to the client in the hand-over phase	considering the enterprise's needs and basic conditions, can put the mechatronic systems into operation, create the necessary documentation, advise the customer on safe operations of the devices, and advise on future technology selection.	considering all basic conditions, can master the start-up of interconnected mechatronic systems and machines, and can provide the necessary documentation including a manual. He/ She can review client needs and confi gure machines that provide solutions. He/She can train the customs where necessary and provide support for safe operating presedures.	require mechat facilities solution and can system implem and ope	s, develop is, n plan the	direct, including scheduling and time management, the start-up of the project from the creation of a proposal to the client's acceptance
6. Supervising and evaluating both the process sequences of mechatronic systems and facilities and the operational sequence (including quality assurance)	He/She can supervise process sequences according to specifications as well as implement any requested quality-control measures.	He/She can independently supervise the process sequences, evaluate the results, operate an accompanying statistic process control (SPC) for the quality control plan, and prepare simple work schedules, including production schedule and	procedures. He/She can operate and the		of complex c systems uments well as nof nt, material sis, and	He/She can optimise the process cycles of mechatronic production lines, provide instructions on modifying the PPS systems (e.g., adjustment to SAP systems) and introduce quality systems for continuous improvement processes (CIP/KVP).
7. Installing, confi guring, programming and testing hardware and software components for control and regulation of mechatronic systems and facilities	He/She is able to install and confi gure programs for hardware and software components as well as set up simple programmable logic control programs (PLC).	time management. He/She can master the selection of hardware and software for mechatronic systems (e.g., sensors, actuators, interfaces, communication procedures) and can provide and test simple programmable logic control programs (PLC) according to production process	confi gure program-, control-, regulationmechani in mechatronic sys program simple de cooperation with developers), a	confi gure program-, control-, and regulationmechanisms in mechatronic systems, program simple devices (in cooperation with developers), and simulate the program sequence before test, and hardware solutions networks systems; monitor is condition measuring		d mechatronic and can system s with suitable
8. Preparing and distributing the technical information for adjustment of each enterprise's mechatronic systems	He/She can provide descriptions and designs of mechatronic subsystems and is familiar with the basic CAD applications.	requirements. He/She can fully under management of technical information mechatronic systems and adapt these document enterprise's specific or requirements.	operational se separately in c and can prepare connections and up maintenance s according to an He/She can		sequences in order to un s and draw ance and pro that the syst or ents' function tly assess ent the wear of the	duction procedures. em parameters are and can
9. Diagnosing and repairing malfunctions with mechatronic systems and facilities, advising	He/She can diagnose and repair errors and malfunctions on the simple components and devices in the mechatronic systems. He/She can use	He/She can independently correct problems in mechatronic production equipment with the help of (computer-aided) diagnostic systems and the use	repair errors and disturb complex mechatronic equi able to advise clients on sources	errors and disturbances in complex mechatronic equipment and is able to advise clients on how to avoid		ctions in the nic nt, a monitoring and c

mechatronic

Learning outcomes

Time	Content	Learning Outcome		
hours		What can the Student (S) do		
	1. Getting s	started		
4	Reply:	S is able to explain and carry out a		
	The students will make some basic	PLC program, and recall ₃ previously		
	instructions with PLC control	learned items of PLC controls		

BUS SYSTEMS 2. Basics of Bus Systems 2 Difference between wired I/O and bus S is able to compare wired I/O and S is abl	
2 Difference between wired I/O and bus S is able to compare, wired I/O at	
system system concerning the idea a	ıd
the advantages of a Bus System	
S is able to differentiate ₅ and	
explain ₆ the differences between	
wired I/O and Bus	
3. Common Bus Systems	
2 Standard Bus systems: Profibus, AS-I, S is able to explain, the function of	f
Ethernet the standard bus systems.	
Factory level, cell level, field I/O S is able to explain the different	
level's of Bus systems and how th	ey
work together.	
4. Cabeling	
4 Cabeling and connections S is able to explain differents in	
three different bus system (Ethern	et,
Profibus, AS-i).	
Differences between bus systems,	
placement in cabelways etc. S is able to carry out ₁₀ connection	5
and explain the principes of placin	
cables	-
5. ProfibusDP Building Network	

2 Profibus net	work	S is able to carry out ₁₁ cabeling and					
		connections in a network consisting					
		of PLC (Master) and a I/O -station					
		(Slave)					
Different pro	tocols, cabeling distance's						
	ig a profibus network	S is able to explain the limits of					
		cabeling procedures					
	6. Profibus Confi						
2 Configuration	n of a Profibus DP –	S is able to explain the idea of					
Master-Slave		configuration and carry out ₁₃					
I Tastel Siave	TICEVIOLIC	configuration procedure					
		configuration procedure					
Licina a conf	iguration tool (software)	S is able to carry out ₁₄ configuring					
USING a COM	7. Profibus Ta						
4 Taking over							
T Taking over	the ProfibusDP network	S is able to carry out 15 I/O —test. S is					
		able to explain 16 the system of					
		addressing in Profibus Network					
	./. C. DI C						
 	st's for PLC-system with						
 	work. Finding out I/O						
from substat	tion and using them						
	8. Network expansion						
4 Making the r	network larger.	S is able to recognise ₁₇ and recall ₁₈					
		the the network properties and					
		procedures of cabeling and taking					
		over					
Adding a new	w Profibus -module to						
•	vork. Students will now						
	nole thing (cabeling,						
	and take over) again						
	9. ProfibusDP Fau	t situations					
4 Possible faul	t situations and diagnosis	S is able to check 19 situations with					
tool's		diagnostic tool's.					
Having a fau	ılt situation and finding it	S is able to organize the procedure					
	iagnostic tool's	of finding out and solving faults					
with using u	lagillostic tools	of illiuming out and solving faults					
	10. AS-I Net	work					
4 Building an	4S-I network	S is able to carry out 21 cabeling and					
		connections in a network consisting					
		of PLC (Master) and a I/O -station					
Connocting	the AS-I network to	(Slave)					
		(Slave)					
Profibus net	WOLK						
	11 AC T T-L:						
1 T-1	11. AS-I Takir ne AS-I network	S is able to carry out 22 I/O -test. S is					
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	Students will make a little AS-I network and connect it to previously built-up Profibus Network	able to explain ₂₃ the system of addressing in AS-i Network S is able to compare ₂₄ the differences between AS-I and Profibus
	12. Ethernet N	etwork
8	Building an Ethernet network	S is able to explain 25 principes of cabeling. S is able to explain 26 the main features of Ethernet network
	Building a little Ethernet network	S is able to carry out ₂₇ cabeling of Ethernet network
	13. Written	test
4	Written test of central theoretical items Profibus, AS-I and Ethernet network	
	14. Practical	
8	to some machine or conveyor.	S is able to organise ₂₈ network cabeling work. S is able to carry out ₂₉ connections and is able to check ₃₀ I/O:s and network functions in taking over. S is able to critic ₃₁ his own work.

Knowledge	Remember	Understand	Apply	Analyze	Evaluate	Create
factual knowledge (knowing WHAT)	17 3 18	4 24 1 6 9 25	10 13	5	19	
causal knowledge (knowing WHY))		7 12			31	
procedural knowledge (knowing HOW)		8 16 23 26	2 11 14 15 21 22 27 29	20 28	30	