TEC













Hydraulic

| Competence | Steps of competence | develop | ment | | | | | |
|---------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|
| area | | | | | | | | |
| 1. Maintaining and assuring the reliability of mechatronic systems | She/he can perform the basic scheduled maintenance on mechatronic machines and systems and adhere to the equipment maintenance plans | mainten procedu mechatr such as t service o mainten and, if fa | res for onic systems the use of documents and ance plans aced with new ses, can make ssary | She/he can us preventive maintenance to the trouble-free operation of mechatronic s. In addition, he modify operation of implement qui assurance mea | ystems. e/she can ional | She/he can develop the necessary procedures for maintenance of mechatronic devices and systems, and can schedule the maintenance and quality-assurance procedures. | | |
| Installing and dismantling mechatronic systems and facilities | She/he can use writte instructions to install dismantle individual components (sensors, actuators, drives, mot transport systems, rac form a functional gro mechatronic systems | and ors, | She/he can mas installation and of mechatronic use several tech (mechanics, hy pneumatics, ele- mechanics, ele- up the connexion technology, and efficiency of the system | dismantling systems that mologies draulics, etrical- etronics), set d check the | She/he can provide independent mechatronic solutions for the construction of production lines, assure their overall ability to function, and, in addition, can use both existing and modified standard components | | | |
| Installing and adjusting mechatronic components in systems and production lines | She/he is able to insta adjust standardized mechatronic compone e.g. individual electro pneumatic valves, ser and actuator units. | ents, | She/he can inst components of subsystems (e.g drives, measuri transport system | mechatronic g., linear ng systems, | c complex mechatronic facilities that include diverse | | | |

Designing, adapting, and building mechatronic systems and facilities on the basis of client needs and site plans

She/he can use machine tools controlled either manually or via. computerprogram to fabricate (according to production designs and customer requirements) the individual components. for mechatronic systems. He/she can provide simple designs and descriptions of mechatronic subsystems and can use basic CAD applications.

She/he can build simple mechatroni by using drawing and can install the devices according to specific production needs. She/he can act on extensive knowledge of standards and regulations (e.g. on surface treatments) use CAD's more advanced functions (e.g. interference

check).

She/he can build mechatroni c systems by using both subsystems original constructio engineering techniques and previously designed parts. She/he fully understands CAD functions and can document system. development s (parts lists, descriptions of function, operating instructions). and is able to

She/he can design and build autonomous mechatroni subsystems and, with suitable measuring and testing facilities, can assess the necessary production accuracy. She/he can document the results with qualitycontrol systems.

She/he can make independent adaptations to the various devices (including selection of drives, sensors, SPS) and can use CNC programs. for building the system. She/he can, through a digital mock up, assemble and simulate the functioning system and use computeraided computatio ns (e.g. FEM). She/he can perform cost-benefit

analyses

(e.g. as a

basis for

deciding

whether

components

should be

bought or

individually

constructed.)

She/he can independent ly develop complex mechatroni c systems and can calculate the economic usefulness of the system. She/he can optimise CNC programs for the manufacturin. g of complex mechatronic devices and systems and monitor the automated quantity of an open loop control system.

| 5. Putting | She/he can. | She/he, after | She/he, after consideri | ng the | She/he o | an | She/he can | |
|--------------|---------------|---------------------|------------------------------------------------------|----------------------------|----------------|------------------------------|-------------|--|
| mechatronic | | considering the | enterprise's needs and | | evaluate | | direct. | |
| systems into | _ | enterprise's needs | conditions, can put the | | custome | | including | |
| operation | specificatio | and basic | | | requiren | | scheduling | |
| and | ns and | conditions, can | mechatronic systems i | | for | | and time | |
| providing | blueprints. | put the | operation, create the n | mechatro | onic | managemen | | |
| clients with | | mechatronic | documentation, advise | facilities | | t, the start- | | |
| technical | mechatroni | systems into | customer on safe opera | ations of | develop | - | up of the | |
| and | c devices | operation, create | the devices, and advise | e on | solution | | project | |
| economic | into | the necessary | future technology sele | ction. | can plan | | from the | |
| support | operation | documentation. | She/he can review clie | | system's | | creation of | |
| support | and provide | | and configure machine | impleme | | a proposal | | |
| | support to | customer on safe | provide solutions. | n and | | to the | | |
| | the client in | | She/he can train the cust | operatio | n | client's | | |
| | the hand- | devices, and | | | operation | | acceptance. | |
| | over phase. | advise on future | where necessary and pro support for safe operatin | | | acceptance. | | |
| | over pinase. | technology | | | | | | |
| | | selection. | procedures. | | | | | |
| 6 | She/he can | She/he can | She/he can operate and | master She/he can optimise | | | | |
| Supervising | supervise | independently | _ | oring of | | can opulnise ocess cycles | | |
| and | process | supervise the | facilities, choose | ning or | of mechatronic | | | |
| evaluating | sequences | process | testing and monitoring | nic: | | ction lines. | | |
| both the | according | sequences, | plans, set up the | sing | | e instructions | | |
| process | to | evaluate the | accompanying SPC, | -mg | on modifi | | | |
| sequences of | | results, operate an | seek the optimal | to and | | rstems (e.g. | | |
| mechatronic | | accompanying | results of the | PPS system | | ment to SAP | | |
| systems and | as wen | statistic process | production line | well as op | | - | | |
| facilities | implement | control (SPC) for | according to material- | control for | | | | |
| and the | amy | the quality control | | optimisati | | | | |
| operational | requested | plan, and prepare | work schedules | machinery | | contin | tems for | |
| sequence | quality- | simple work | including standard | arrangeme | | | | |
| (including | control | schedules, | production times. | material f | - | • | improvement | |
| quality | measures. | including | production than | analysis, a | | (CIP/KVP). | | |
| assurance) | | production | | scheduling | | (| | |
| assurance) | | schedule and time | | | | | | |
| | | mana gement. | | | | | | |
| <u> </u> | | | | | | | | |

| _ | | | | | | | | | | |
|----------------|---------------------|---------|--------------------------------------|--------------------------------------------------------------------------------------|-------------------------------------------------|------------------------|--|--|--|--|
| 7. Installing, | She/he is able to | | can master the | | _ | She/he can develop, | | | | |
| configuring, | install and | | on of hardware and | | figure program-, | test, and configure | | | | |
| programmin | configure | softwa | re for mechatronic | | trol-, and regulation- | hardware and | | | | |
| g and testing | programs for | - | is (sensors, actuators, | | chanisms in | software solutions for | | | | |
| hardware | hardware and | | ces, communication | | chatronic systems, | networked | | | | |
| and software | software | _ | ures) and can provide | | gram simple devices | mechatronic systems; | | | | |
| components | components as | | t simple software | | co-operation with | and can monitor | | | | |
| for control | well as set up | | l programs (PLC) | | elopers), and | system conditions | | | | |
| and | simple software | accord | ing to production | | ulate the program | with suitable | | | | |
| regulation of | control programs | proces | s requirements. | seq | uence before start- | measuring and | | | | |
| mechatronic | (PLC). | | | up. | | visualisation tools. | | | | |
| systems and | | | | | | | | | | |
| facilities | | | | | | | | | | |
| 8. Preparing | She/he can | | can fully understand | | he is able to analyse c | _ | | | | |
| and | provide | | nagement of technical | | uences separately in or | | | | | |
| distributing | descriptions and | | ation documents for | | nections and draw up i | | | | | |
| the technical | designs of | | tronic systems and can | _ | duction procedures. Sh | | | | | |
| information | mechatronic | _ | e and adapt these | that the system parameters are important for the | | | | | | |
| for | subsystems and is | | ents according to an | equipments' functions and can independently assess and document the wear and general | | | | | | |
| adjustment | familiar with the | _ | _ | | _ | | | | | |
| of each | basic CAD | operati | ing requirements. | con | ditions of the mechatro | onic equipment. | | | | |
| enterprise's | applications. | | | | | | | | | |
| mechatronic | | | | | | | | | | |
| systems. | 22 2 | | 01 0 1 1 | | 01 0 1 | | | | | |
| 9. | She/he can diagnos | e and | She/he can independen | tly | She/he can diagnose | | | | | |
| Diagnosing | repair errors and | | correct problems in | | repair errors and | develop, through | | | | |
| and repairing | malfunctions on the | | mechatronic production | | disturbances in comp | • | | | | |
| malfunctions | simple components | and | equipment with the hel | р | mechatronic equipme | | | | | |
| with | devices in the | | of (computer-aided) | | and is able to advise | the mechatronic | | | | |
| mechatronic | She/he can use the | ь. | the rece of owners content | | clients on how to avo sources of malfunction | | | | | |
| facilities, | | | the use of expert system | us, | | | | | | |
| advising | measuring, and diag | | databases, and error documentations. | | through changes or upgrades in the | diagnostic | | | | |
| clients on | tools. | shostic | GOC Unitellitations. | | equipment and system | system. | | | | |
| avoiding | | | | | equipment and system | | | | | |
| malfunctions | | | | | | | | | | |
| , and | | | | | | | | | | |
| modifying | | | | | | | | | | |
| and | | | | | | | | | | |
| expanding | | | | | | | | | | |
| mechatronic | | | | | | | | | | |
| systems and | | | | | | | | | | |
| facilities | | | | | | | | | | |
| incinues | | | | | | | | | | |

| Time | Content | Learning Outcome |
|-------|----------------------------------------------|--------------------------------------------------------------------------------------|
| Hours | | What can the Student (S) do |
| | | Title Carr and Deaderic (D) ao |
| | Physics of hydraulics. | The apprentice/student is able to |
| | Calculation of Piston force, speed and flow. | carry out _{3-FP} (1) minor changes or |
| | | expansions of the existing hydraulics and |
| | Handling and precaution of hydraulic oil. | electrohydraulic equipment from |
| | | documentation, as well as being able to |
| | Principle diagrams of hydraulics. | differentiate and select 4-CaCo (2) |
| | | components for this. |
| | Basic hydraulic components. | |
| | Pumps. | The apprentice/student is able to |
| | Tank, cooler and filters. | implement _{3-FPCo} (3) and checks _{5-FCaPCo} |
| | Cylinders. | (4) hydraulics and electrohydraulic |
| | Valves for control of hydraulics directions | equipment according to specifications |
| | flow and pressure. | i.e. do control measurement; adjust |
| | Electrical controlled valves. | documentation for the equipment |
| | | according normal standards. The |
| | Build up of hydraulics circuits according | apprentice/student is able to |
| | diagrams on work bench. | summarize _{2-FCa} (5) documentation being |
| | | used to instruction of the operators. |
| | Adjusting flow, pressure and speed. | |
| | | The apprentice/student is able to |
| | Safety in hydraulics. | organize _{4-FCaPCo} (6) preventive |
| | | maintenance on hydraulics and |
| | | electrohydraulic equipment in use. |
| | | |
| | | The apprentice/student is able to |
| | | differentiate between _{4-FaP} (7) |
| | | instruments. The apprentice/student is able |
| | | to generate _{6-FcaP} (8) systematically, methodic |
| | | faultfinding and fault correcting until |
| | | component level. |
| | | |
| | | The apprentice/student is able to carry out ₃ . |
| | | P (9) exchange of components according to |
| | | documentation. |
| | | |
| | | The apprentice/student is able to |
| | | produce _{6-FCaP} (10) documentation and |
| | | manuals to minor new contructions or |
| | | minor modificated equipment. |
| | | The appropries/student is able to |
| | | The apprentice/student is able to interpret _{2-F} (11) the specific demands |
| | | with regard to safety and environmetal |
| | | hydraulics and electrohydraulic |
| | | equipment. |
| | | equipinent |
| | | |
| | | |

| Cognitive | Re- men | ıber | Und [2] | ersta | nd | | | | | App [3] | Apply Analyzo [3] [4] | | lyze | • | | Evaluate [5] | | Create [6] | |
|---------------------------------------------|-------------|-----------|--------------|--------------|-------------|-------------|-----------|----------------------|------------|------------------------|--------------------------|-----------------|------------|-------------|----------|-----------------|------------|---------------|-----------|
| Knowledge | Recognizing | Recalling | Interpreting | Exemplifying | Classiyfing | Summarizing | Inferring | Comparing,, Contrast | Explaining | Carry ing out, Execute | Implementing | Differentiating | Organizing | Attributing | Checking | Critiquing | Generating | Planning | Producing |
| factual knowledge (knowing WHAT) | | | 11 | | | 5 | | | | 9 | 3 | 7 | 6 | | 4 | | 88 | | 10 |
| causal knowledge (knowing WHY) | | | | | | 5 | | | | | | 7 | 6 | | 4 | | 8 | | 10 |
| procedural knowledge (knowing HOW) | | | | | | | | | | 1 | 3 | 7 | 6 | | 4 | | 8 | | 10 |
| conditional lanowledge (knowing WHEN) | | | | | | | | | | | 3 | 2 | 6 | | 4 | | | | |